

REMARKS ON THE PERTURBATION FORMULAE
OF BRILLOUIN AND WIGNER

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Consider the eigenvalue problem of a Hermitian matrix H_{kl}

$$(1) \quad \sum_l H_{kl} C_l = F C_k \qquad \sum_k C_k^* H_{kl} = C_l^* F$$

in which H_{kl} differs only little from a diagonal matrix $E_k \delta_{kl}$:

$$(2) \quad H_{kl} = E_k \delta_{kl} + V_{kl}$$

1)
Brillouin has established the following relation which -- in case of convergence of the infinite series -- is satisfied by eigenvalues

$$(3) \quad F - E_1 = V_{11} + \sum_k \frac{V_{1k} V_{kl}}{F - E_k} + \sum_{k,l} \frac{V_{1k} V_{kl} V_{l1}}{(F - E_k)(F - E_l)} + \dots \quad (k, l \neq 1)$$

In this series one of the indices -- in our formula the index 1 -- plays a part of its own. If $|V_{1k}| \ll |E_k - E_1|$ for all k's, the first two or three terms in (3) are often very useful to calculate the perturbed eigenvalue which are near to E_1 , even if the V's and E's are such that the series does not converge. The difference between (3) and the closely analogous series of the customary perturbation theory of Rayleigh-Schrödinger lies in the appearance of the eigenvalue in the right member of (3). Thus Schrödinger's well known second approximation is given by

$$(4) \quad F - E_1 = V_{11} + \sum_k \frac{V_{1k} V_{k1}}{E_1 - E_k}$$

2)
Lennard-Jones was the first to point out the importance in some

1) L. Brillouin, Journ. de Ph. 4, 1, 1933.
2) J. E. Lennard-Jones, Proc. Roy. Soc., London, A129, 598, 1930.

$$(7) \quad C^*H \equiv C^*(D + V' + V'') = C^*F,$$

where D is the diagonal matrix with elements $E_{k\ell} \delta_{k\ell}$. D , V' and V'' are matrices operating on C^* whereas F is a real number.

From (7) follows

$$C^*V' = C^*(F - D - V'') \quad (8)$$

$$C^*V' \frac{1}{F-D} = C^*(1 - V'' \frac{1}{F-D})$$

$$\begin{aligned} C^* &= C^*V' \frac{1}{F-D} (1 - V'' \frac{1}{F-D})^{-1} \\ &= C^*(V' \frac{1}{F-D} + V' \frac{1}{F-D} V'' \frac{1}{F-D} + V' \frac{1}{F-D} V'' \frac{1}{F-D} V'' \frac{1}{F-D} + \dots) \end{aligned} \quad (9)$$

Reintroducing indices we find from this equation in the first place

$$C_1^* = C_1^* \left(\frac{V_{11}'}{F-E_1} + \sum_k \frac{V_{1k}' V_{k1}''}{(F-E_k)(F-E_1)} + \dots \right) \quad (k \neq 1)$$

or, after dividing by C_1^* and multiplication with $F-E_1$

$$F - E_1 = V_{11}' + \sum_k \frac{V_{1k}' V_{k1}''}{F-E_k} + \dots$$

This is identical with (3) since the accents can be omitted.

In the second place one finds

$$C_k^* = C_1^* \left(\frac{V_{1k}'}{F-E_k} + \sum_l \frac{V_{1l}' V_{lk}''}{(F-E_l)(F-E_k)} + \dots \right) \quad (10)$$

but this is (for $C_1^* = 1$) precisely the same as equation (5) (with $\nu \rightarrow \infty$).

It does not seem as if the introduction of (2) and (6) would help towards simplifying the proof of Wigner's interesting theorem in a significant way.

In the approximation method of Lennard-Jones, all denominators in (4) are replaced by an appropriately chosen average denominator Δ . In this connection we will inquire what will be the

result of (3) if all E_k 's are chosen equal to $E_1 + \Delta$ where E_1 is defined as the matrix element

$$E_1 = H_{11} .$$

Introducing the following abbreviations:

$$(8) \quad \varepsilon = F - E_1, \quad \left\{ (H - E_1)^n \right\}_{11} = a_n$$

we find, after some calculation:

$$(9) \quad \varepsilon = -\frac{a_2}{\Delta - \varepsilon} + \frac{a_3 - \Delta a_2}{(\Delta - \varepsilon)^2} - \frac{(a_4 - a_2^2) - 2\Delta a_3 + \Delta^2 a_2}{(\Delta - \varepsilon)^3} + \frac{(a_5 - 2a_3 a_2) - 3\Delta(a_4 - a_2^2) + 3\Delta^2 a_3 - \Delta^3 a_2}{(\Delta - \varepsilon)^4}$$

If one cuts off after an even number 2ν of terms, the ε value which corresponds to $d\varepsilon/d\Delta = 0$ would--in view of Wigner's theorem--yield the best approximation within the frame of this method.

If H can be written in the form

$$H_{k\ell} = H_{hk} \delta_{k\ell} + \lambda u_{k\ell}$$

where λ is a small parameter, and if one asks only for the contribution to ε which is proportional to λ^2 , one may first of all omit all ε 's in the denominators of (8) and one gets

$$(10) \quad \varepsilon = -\frac{2a_2}{\Delta} + \frac{a_3}{\Delta^2} \quad (\nu = 1)$$

$$(11) \quad \varepsilon = -\frac{4a_2}{\Delta} + \frac{6a_3}{\Delta^2} - \frac{4(a_4 - a_2^2)}{\Delta^3} + \frac{a_5 - 2a_3 a_2}{\Delta^4} \quad (\nu = 2)$$

If we denote the 11-element of a matrix M by a bar:

$$M_{11} = \bar{M}$$

one finds for the terms proportional to λ^2 in the a_n 's

$$(12) \quad a_n = \lambda^2 \frac{u(H - E_1)^{n-2} u}{u}$$

Putting moreover

$$M^{(0)} = \bar{M}, \quad M^{(1)} = \frac{1}{\hbar}(HM - MH), \quad M^{(\nu+1)} = \frac{1}{\hbar}(HM^{(\nu)} - M^{(\nu)}H)$$

which, if one prefers so, can be written also as

$$M^{(\nu)} = \overline{\left(\frac{d}{dt}\right)^\nu M}$$

we find from (12)

$$a_{2\nu+2} = \lambda^2 \overline{\hbar^{2\nu} u^{(\nu)^2}}$$

$$a_{2\nu+3} = \frac{1}{2} \lambda^2 \overline{\hbar^{2\nu+1} i(u^{(\nu+1)}u^{(\nu)} - u^{(\nu)}u^{(\nu+1)})}$$

or

$$a_n = \lambda^2 \overline{\left(\frac{\hbar}{i}\right)^{n-2} u u^{(n-2)}}$$

For (10) and (11) we can therefore write:

$$(14) \quad \frac{\epsilon}{\lambda^2} = -\frac{2\overline{u^2}}{\Delta} + \frac{1}{2} \hbar i \overline{\frac{u^{(1)}u - u u^{(1)}}{\Delta^2}}$$

$$(15) \quad \frac{\epsilon}{\lambda^2} = -\frac{4\overline{u^2}}{\Delta} + 3 \hbar i \overline{\frac{u^{(1)}u - u u^{(1)}}{\Delta^2}} - 4 \hbar^2 \overline{\frac{u^{(1)^2}}{\Delta^3}} + \frac{1}{2} \hbar^3 i \overline{\frac{u^{(2)}u^{(1)} - u^{(1)}u^{(2)}}{\Delta^4}}$$

by variation of Δ one finds the extreme values for ϵ . Thus from

(14) we have simply

$$(16) \quad \frac{\epsilon}{\lambda^2} = -\frac{\overline{u^2}^2}{\frac{1}{2} \hbar i \overline{(u^{(1)}u - u u^{(1)})}}$$

This is the formula of Hassé's⁴⁾ approximation method.

If one asks for the polarizability of a one-electron system we may take for u one of the cartesian coordinates, say x , and (16) gives the well-known approximative expression

⁴⁾ H. R. Hassé, Proc. Cambr. Phil. Soc. 26, 542, 1930.
H. Margenau, Rev. Mod. Phys. 11, 1, 1939.

$$\varepsilon = -\lambda^2 \frac{\overline{x^2}}{\hbar^2/2m}.$$

If, however, one tries to apply (15) to the same problem, one meets the difficulty that in the hydrogen atom the fourth term gets undetermined and that--if expressions containing 6 or more terms are used ($\nu = 3, 4, \dots$)--all terms after the fourth diverge. This probably means that in general (8) will be of little use.

In many quantum-mechanical problems (compare the H_2 -molecule) approximative wave functions can be established although one cannot distinguish between unperturbed Hamiltonian and perturbation energy (like the λu above). In such cases the minimum value which ε can take in the expression (see (9)) might sometimes represent a good second approximation. Putting

$$\varepsilon = -\frac{a_2}{\Delta - \varepsilon} + \frac{a_3 - \Delta a_2}{(\Delta - \varepsilon)^2}$$

one finds easily

$$\varepsilon = \frac{1}{2} \frac{a_3}{a_2} \left(1 - \sqrt{1 + 4a_2^3/a_3^2} \right).$$

which expresses ε in terms of the second and third "moment" of H (comp. (8)).